

# How to Timestamp Transactions for Audit Without a Central Timestamp Authority

If you need legally and forensically defensible timestamps but cannot depend on a single trusted timestamp authority, GPS time, or a network time server, you face a structural problem: whoever issues the time becomes a single point of trust and failure. This guide describes an architectural approach that derives time cooperatively from a mesh of credentialed agents and binds each timestamp to content, an event, or a transaction with a reconstructible audit trail. The approach is the Mesh-Derived Time inventive step, disclosed in U.S. Provisional Application No. 64/049,409. This is an architecture you implement yourself, not a shipping library.

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## What You Are Building

You are building a way to stamp a transaction, document, or event with a time value that an auditor, regulator, or court can later trust, without routing every stamp through one central timestamp authority. Concretely, you want each timestamp to say four things and prove them later: what time it was, who attested to that time, how confident that attester was, and what exact content the time is bound to.

The people who have this problem tend to share a constraint. Financial settlement systems, regulated data pipelines, forensic evidence chains, and multi-party transaction ledgers all need timestamps that survive challenge. But they operate in environments

where a single trusted time source is either a liability (it can be compromised, subpoenaed, or simply go down) or unavailable (contested, disconnected, or spanning multiple jurisdictions that do not accept one another's authorities). You need time that is defensible even when no one party is trusted to define it.

This guide describes an architecture disclosed in a patent filing. It is not a package you install. It gives you the design and the sequence of decisions to build it.

## **Why the Obvious Approaches Fall Short**

The standard tools are real and each is good at what it does, so it is worth being precise about where they leave a gap for this particular problem.

Network Time Protocol distributes time from authoritative servers down a stratum hierarchy. It is a client-server design: clients synchronize against stratum-1 servers that hold the reference. That is exactly right for keeping machines roughly aligned, but the reference is centralized, and NTP by itself does not produce a signed, per-event attestation you can hand to an auditor.

Precision Time Protocol achieves much tighter synchronization for local networks, but it is organized around a master-slave configuration with an elected grandmaster clock. The grandmaster is the reference. Removing the single reference is not what PTP is designed to do.

Satellite time services (such as GNSS-derived time) broadcast time from centrally operated constellations. Acquisition is required to get the time, and denial or spoofing of the signal removes it. The authority is remote and singular.

RFC 3161 trusted timestamping authorities solve the attestation problem directly: a TSA signs a hash of your content with a timestamp. This is genuinely useful and widely used. The structural point is simply that the trust concentrates in the TSA. Its key, its clock, and its availability become the thing an adversary or a court focuses on.

Blockchain timestamping decentralizes the authority, but conventional chains stamp at block-commit granularity, which yields coarse timestamps (commonly minute-scale) rather than a signed time value at the moment of an individual observation.

None of these is a straw man; each is fit for its purpose. The gap they share, for the audit use case, is that a defensible per-event timestamp still rests on some single reference or coarse granularity. The architecture below targets exactly that gap.

## **The Architecture**

The disclosed approach treats time as a cooperatively produced primitive rather than a service you consume from an authority. Per the filing, the mesh-derived time primitive generates and maintains a shared temporal reference frame produced cooperatively by participating agents through inter-agent timing exchanges and admitted temporal anchor observations, without dependence on any specific external timing infrastructure.

The building blocks the spec describes are these:

**Clock-maintaining agents.** Each participating agent maintains its own local clock with characterized drift properties. No agent is the master.

**Inter-agent time-synchronization.** Agents produce governance-credentialed time-synchronization observations between one another through one of several synchronization modalities. These exchanges are what let the mesh estimate how each agent's clock relates to the others.

**Temporal anchor admission.** The mesh can admit governance-credentialed temporal anchor contributions (an external reference offered by a credentialed source) but does not require one. This is the hook for pulling in a high-quality time source without making it the authority.

**Cooperative time-estimation engine.** This determines each agent's time-offset by combining the synchronization observations and any anchor contributions. This is the core: time is an estimate over the graph, not a value handed down.

**Transitive time-propagation.** When an agent is not directly synchronized to an anchor, its offset is derived through neighbor references, so agents deep in the mesh still get a time bearing.

**Drift compensation and clock-model learning.** Local-clock drift is continuously compensated by fresh synchronization exchanges, and per-agent drift characterizations are refined over time through governance-credentialed training.

**Time-uncertainty propagation.** Synchronization uncertainty is propagated through the temporal graph, producing a per-agent time-uncertainty estimate. Every time value carries how sure the mesh is about it. This is essential for audit: an honest timestamp states its own error bounds.

**Adversarial-time rejection.** Spoofed, injected, or otherwise inadmissible synchronization observations are rejected rather than folded into the estimate.

**Anchor-less bootstrap.** When no anchor is available at all, the mesh produces a relative-only temporal frame. You still get consistent ordering among participants even with no external time.

**Time-frame federation.** Independently maintained temporal frames can be aligned, so two meshes under different authorities can be reconciled.

On top of the time frame sits the piece that matters most for your use case: the **governance-credentialed timestamp attestation interface**. Per the spec, it produces timestamp observations that carry the attesting agent's authority credential, the mesh-derived time value, the estimated time uncertainty, and a cryptographic signature. Its components include a request receiver, an admissibility evaluator that

applies governance-policy rules, a composer that assembles the signed timestamp observation, an observation-binding mechanism that cryptographically binds the timestamp to specific content, document, event, or other content through content-addressing, a multi-attester consensus composer that produces a timestamp signed by multiple independent attesters for high-assurance cases, and a lineage recorder.

The spec enumerates the attestation patterns this supports: single-attester, multi-attester consensus (a policy-defined quorum of independent attesters), authority-hierarchy (attested at a level appropriate to the content), content-bound (bound to content via content-addressing), event-bound (certifying a credentialed event occurred), transaction-bound (attesting a multi-party transaction), continuity-bound (attesting identity continuity), and composite combinations of these.

The audit property is the payoff. Per the filing, a timestamp's lineage, the synchronization chain that produced the attesting agent's time, the composite admissibility evidence, and the authority-credential chain are all reconstructible from the governance lineage, supporting regulatory, legal, forensic, and governance-enforcement audit. An auditor does not have to trust the number; they can reconstruct how it was derived.

## **How to Approach the Build**

Work in this order. Each step maps to a mechanism above.

**1. Define your credential and policy model first.** Everything is governance-credentialed, so before any timing code, decide who is allowed to attest, what an authority credential contains, and what your admissibility policy accepts or rejects. This is a prerequisite, not an afterthought.

**2. Stand up clock-maintaining agents.** Give each agent a local clock and a way to characterize its drift. Do not designate a master.

**3. Implement synchronization exchanges.** Have agents produce signed time-synchronization observations with each other. An illustrative interface sketch, faithful to the spec's fields and clearly not a finished implementation:

```
// illustrative only; you implement the mechanisms
SyncObservation {
  fromAgent, toAgent
  localSendTime, localRecvTime // for offset estimation
  authorityCredential // governance-credentialed
  signature
}
```

**4. Build the cooperative time-estimation engine.** Combine synchronization observations (and any admitted anchors) into a per-agent time-offset. Add transitive propagation so agents without a direct anchor inherit an offset through neighbors.

**5. Propagate uncertainty, and never drop it.** Carry a time-uncertainty estimate alongside every offset. Downstream consumers, and auditors, rely on it.

**6. Add adversarial-time rejection before you trust any exchange.** Filter spoofed or injected observations at admission. If you skip this, an attacker moves the whole frame.

**7. Implement anchor-less bootstrap.** Make sure the mesh produces a usable relative-only frame with zero external anchors, so ordering survives full disconnection.

**8. Build the timestamp attestation interface on top.** Now compose signed timestamp observations carrying credential, time value, uncertainty, and signature. Add content-binding via content-addressing so a timestamp is provably tied to one exact payload:

```
// illustrative only
TimestampObservation {
  attester, authorityCredential
  meshTimeValue, timeUncertainty
  contentAddress // binds to specific content/event/txn
  signature
}
```

**9. Pick the attestation pattern per use case.** For a multi-party transaction, use the transaction-bound pattern; for high assurance, add multi-attester consensus so a quorum of independent attesters sign. Match the pattern to the assurance you owe your auditor.

**10. Record lineage at every step.** Log each synchronization exchange, anchor admission, estimation event, rejection, federation, and attestation into the lineage record. The audit guarantee is only as good as what you recorded.

**11. Optionally fuse external time, but through admissibility.** If you have GNSS, network, or atomic time, admit it as evidence through your admissibility evaluator rather than as ground truth, so no single external source becomes the authority.

## What This Does Not Give You

This is an architecture disclosed in a patent filing, not a drop-in library, an SDK, or a downloadable package. There is nothing here to `npm install`. You implement every mechanism yourself, and the design choices (credential format, admissibility policy, synchronization modality, cryptographic primitives) are yours to make.

The approach has not been presented here with benchmarks, precision figures, or production results, and this guide does not claim any. The spec describes what the primitive does and how it is structured; it does not authorize you to promise a specific

accuracy, throughput, or that it "just works." Real synchronization precision will depend entirely on your clocks, your modality, your network, and your drift models.

It is also not automatically the right tool. If you already trust a single authority and are comfortable with that trust, an RFC 3161 timestamping authority is simpler. If you only need machines loosely aligned, NTP is enough. If you have one tightly controlled LAN, PTP will give you tighter synchronization with less to build. This architecture earns its complexity specifically when you cannot or will not concentrate trust in one time source and you need per-event, content-bound, auditable timestamps across parties or jurisdictions.

Finally, an anchor-less mesh gives you a relative-only frame: consistent ordering among participants, not a claim about absolute civil time. If your audit requires wall-clock time tied to an external standard, you must admit an anchor, and the strength of that claim inherits from that anchor.

## **Disclosure Scope**

The mesh-derived time approach described here, including cooperative time estimation without a central authority and the governance-credentialed timestamp attestation interface, is disclosed in U.S. Provisional Application No. 64/049,409. This guide is educational: it explains the disclosed architecture so a skilled developer can understand and build it themselves. It is not a warranty, a specification of any product, or an offer of software, and nothing here should be read as a guarantee of performance, fitness, or availability of any implementation.

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## **Mesh-Derived Time** ([/mesh-time](#))

[All 40 steps](#) → ([/inventive-steps](#))

Master-less consensus time. Joint spatial-temporal optimization. Multi-attester timestamps.

Provisional application

## **PRIMARY TECHNICAL DISCLOSURE**

- [Mesh-Derived Time: Master-Less Consensus and Joint Spacetime Optimization \(/articles/mesh-derived-time-master-less-consensus-and-joint-spacetime-optimization\)](/articles/mesh-derived-time-master-less-consensus-and-joint-spacetime-optimization)

## **SECONDARY TECHNICAL**

- [Master-Less Consensus Time \(/articles/mesh-time/master-less-consensus\)](/articles/mesh-time/master-less-consensus)
- [Per-Agent Learned Drift Models \(/articles/mesh-time/per-agent-drift-models\)](/articles/mesh-time/per-agent-drift-models)
- [Ranging-Piggyback Synchronization \(/articles/mesh-time/ranging-piggyback-sync\)](/articles/mesh-time/ranging-piggyback-sync)
- [Joint Spatial-Temporal Graph \(/articles/mesh-time/joint-spacetime-graph\)](/articles/mesh-time/joint-spacetime-graph)
- [Multi-Attester Consensus Timestamping \(/articles/mesh-time/multi-attester-consensus-timestamp\)](/articles/mesh-time/multi-attester-consensus-timestamp)
- [Time-Frame Federation Across Mesh Regions \(/articles/mesh-time/time-frame-federation\)](/articles/mesh-time/time-frame-federation)
- [Integrated Relativistic Correction \(/articles/mesh-time/relativistic-correction\)](/articles/mesh-time/relativistic-correction)
- [Anti-Spoofed Time Observations \(/articles/mesh-time/anti-spoofed-time\)](/articles/mesh-time/anti-spoofed-time)
- [Anchorless Time Bootstrap \(/articles/mesh-time/anchorless-bootstrap\)](/articles/mesh-time/anchorless-bootstrap)
- [Audit-Grade Time Attestation \(/articles/mesh-time/audit-grade-attestation\)](/articles/mesh-time/audit-grade-attestation)

## **APPLICATIONS · GENERAL**

- [Coordinated Time for Autonomous Fleets in GNSS-Denied Operations \(/articles/mesh-time/autonomous-fleet-coordinated-time\)](/articles/mesh-time/autonomous-fleet-coordinated-time)
- [Legally Defensible Settlement Timestamps Without Single-Source Clock Authority \(/articles/mesh-time/financial-settlement-attested-time\)](/articles/mesh-time/financial-settlement-attested-time)
- [GNSS Time Denial: Holding Critical Infrastructure Timing When GPS Is Jammed or Spoofed \(/articles/mesh-time/gnss-time-denied-critical-infrastructure\)](/articles/mesh-time/gnss-time-denied-critical-infrastructure)
- [5G/6G Network Timing Without Master-Broadcast Dependency \(/articles/mesh-time/5g-6g-network-timing\)](/articles/mesh-time/5g-6g-network-timing)
- [How to Timestamp a Blockchain Without Consensus Overhead \(/articles/mesh-time/blockchain-time-without-consensus\)](/articles/mesh-time/blockchain-time-without-consensus)
- [Tamper-Evident Trading Timestamps Without a Single GPS Grandmaster \(/articles/mesh-time/high-frequency-trading-time\)](/articles/mesh-time/high-frequency-trading-time)
- [Post-Quantum Migration for Timestamping Authorities \(/articles/mesh-time/post-quantum-cryptographic-time\)](/articles/mesh-time/post-quantum-cryptographic-time)
- [GPS-Independent Spacecraft Time Coordination for Satellite Constellations \(/articles/mesh-time/spacecraft-coordinated-time\)](/articles/mesh-time/spacecraft-coordinated-time)

## APPLICATIONS · SPECIFIC

- [IEEE 1588 PTP vs Master-Less Governed Mesh Time \(/articles/mesh-time/ieee-1588-ptp\)](/articles/mesh-time/ieee-1588-ptp)
- [Microchip SyncE Lacks Master-Less Consensus Time \(/articles/mesh-time/microchip-syncE\)](/articles/mesh-time/microchip-syncE)
- [Microchip SyncServer Alternative: Governed Master-Less Time Consensus \(/articles/mesh-time/microsemi-tsync\)](/articles/mesh-time/microsemi-tsync)
- [Meinberg NTP Alternative: Governed Master-Less Time Consensus \(/articles/mesh-time/meinberg-ntp\)](/articles/mesh-time/meinberg-ntp)
- [Oscilloquartz Alternative: Governed Master-Less Time Consensus \(/articles/mesh-time/oscilloquartz-timing\)](/articles/mesh-time/oscilloquartz-timing)
- [Spectracom Orolia Alternative: Governed Master-Less Time Consensus \(/articles/mesh-time/spectracom-orolia\)](/articles/mesh-time/spectracom-orolia)
- [Trimble Thunderbolt Alternative: Master-Less Mesh Time Consensus \(/articles/mesh-time/trimble-thunderbolt\)](/articles/mesh-time/trimble-thunderbolt)
- [White Rabbit \(CERN\) vs Mesh Time: Master-Less Timing Consensus \(/articles/mesh-time/white-rabbit-cern\)](/articles/mesh-time/white-rabbit-cern)
- [DigiCert timestamping \(RFC 3161\) alternative: mesh-derived, governance-credentialed time attestation for legal and forensic audit \(/articles/mesh-time/digicert-timestamping\)](/articles/mesh-time/digicert-timestamping)

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[Mesh-Derived Time overview → \(/mesh-time\)](/mesh-time)