

Operator Intent for Autonomous-Policing De-Escalation Systems

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Where Autonomous Policing Operates

Boston Dynamics Spot deployments by NYPD, Massachusetts State Police, and other agencies; Knightscope security-robotics deployments; emerging autonomous-patrol research; non-lethal de-escalation robotics in early-stage research. Each deployment faces authority-composition questions that current architecture handles implementationally.

What Intent Composition Provides

Officer-of-record intent (mission scope, target assignment, engagement boundary). Supervisor intent (operational approval). Departmental intent (policy scope, jurisdictional limits). Civilian-oversight intent (public-safety boundary, transparency requirements).

Each is credentialed and admits structurally. De-escalation operations admit through composite admissibility; non-de-escalation transitions admit through declared escalation authority; civil-rights-relevant audit reads structurally.

Civilian Oversight and Transparency

Emerging police-AI oversight frameworks (NYC AEDT-like, federal proposed legislation, ACLU advocacy) push toward structurally-supported oversight. The architectural substrate supports the trajectory.